IV B.TECH I SEMESTER	L	Τ	Р	INTERNAL MARKS	EXTERNAL MARKS	TOTAL MARKS	CREDITS
	3	0	0	30	70	100	3
Code: R20CC4OE08	<b>EMBEDDED AND REAL TIME OPERATING SYSTEMS</b> (Open Elective - IV)						

### **COURSE OBJECTIVES:**

- 1. To survey the basics of an embedded system.
- 2. To survey the general structure of a real-time system.
- 3. To develop task scheduling and task communication algorithms.
- 4. To develop task synchronization algorithms.
- 5. To identify the design methods of embedded systems.

#### **COURSE OUTCOMES:**

After completion of the course, the student will be able to

CO1: Survey the basics of an embedded system. [K4]

CO2: Survey the general structure of a real-time system. [K4]

CO3: Develop task scheduling and task communication algorithms. [K3]

CO4: Develop task synchronization algorithms. [K3]

CO5: Identify the design methods of embedded systems. [K3]

#### SYLLABUS:

### **UNIT-I: INTRODUCTION TO EMBEDDED SYSTEMS**

Embedded system vs. General computing system, classification, major application areas, purpose of embedded systems, core of embedded system, memory, sensors and actuators, communication interface.

#### **UNIT-II: INTRODUCTION TO RTOS**

Operating System basics, types, RTOS, Architecture of the Kernel, Kernel objects, tasks/process and threads, Context Switching, Interrupt service routines- Interrupt latency, interrupt response time, interrupt recovery time, How to choose an RTOS?

#### UNIT-III: TASK SCHEDULING AND TASK COMMUNICATION

Task Scheduling - Types of multitasking, non-preemptive and preemptive scheduling algorithms, Task Communication - shared memory, pipes, memory mapped objects, message passing, message queue, mailbox, signalling, RPC and sockets.

#### **UNIT-IV: TASK SYNCHRONIZATION**

Task Communication/Synchronization issues, racing, deadlock, Conditions favoring deadlock situation, deadlock handling, the dining philosopher's problem, Task Synchronization techniques-Semaphore, Mutex,

#### **UNIT-V: DESIGN TECHNOLOGY**

Introduction, Automation, Synthesis, Parallel evolution of compilation and synthesis, Logic Synthesis, RT synthesis, Behavioural Synthesis, Systems Synthesis and Hardware/Software Co-Design.



# **TEXT BOOKS:**

- 1. Introduction to embedded systems, Shibu. K.V, TMH, 2009.
- 2. Embedded / Real Time Systems, KVKK Prasad, Dreamtech Press, 2005.
- 3. Embedded System Design, A Unified Hardware/Software Introduction, Frank Vahid, Tony D. Givargis, John Wiley, 2002.

### **REFERENCE BOOKS:**

- 1. 8051 Microcontroller & Embedded Systems using Assembly and C, Ayala & Gadre: Cengage
- 2. Embedded Systems, Rajkamal, TMH, 2009.
- 3. Embedded Software Primer, David Simon, Pearson.
- 4. The 8051 Microcontroller and Embedded Systems, Mazidi, Pearson.

## **WEB RESOURCES:**

- 1. https://www.youtube.com/watch?v=F321087yYy4
- 2. https://www.youtube.com/watch?v=JIr7Xm\_riRs&list=PLEBQazB0HUyQ4hAPU1cJED6t3DU0 h34bz&index=2
- 3. https://www.youtube.com/watch?v=95yUbClyf3E&list=PLEBQazB0HUyQ4hAPU1cJED6t3DU0 h34bz&index=3
- 4. https://www.youtube.com/watch?v=pHJ3lxOoWeI&list=PLEBQazB0HUyQ4hAPU1cJED6t3DU 0h34bz&index=5
- 5. https://www.youtube.com/watch?v=5JcMtbA9QEE&list=PLEBQazB0HUyQ4hAPU1cJED6t3DU 0h34bz&index=7

